

# Dependency of Geodynamic Parameters on the GNSS Constellation

S. Scaramuzza,  
R. Dach, G. Beutler, D. Arnold, A. Jäggi

*Astronomical Institute, University of Bern, Switzerland*

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IGS Workshop, 08.–12. February 2016, Sydney, Australia

# Overview

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Introduction and Motivation

Geocenter Parameters

Earth Rotation Parameters

Summary and Conclusion

# Levels of Multi-GNSS Analysis

GPS

GLONASS

recCLK

CRD

TRP

GCC

ERP

ORB

satCLK

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recCLK+ISB

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  - plane-wise **ERP** (6 for GPS and 3 for GLONASS), and
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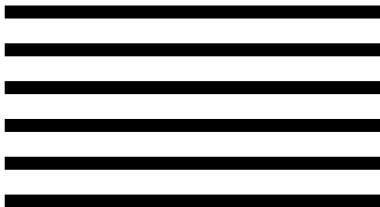
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# Principle of Solution Generation

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GPS



GLONASS



# Principle of Solution Generation

GPS



ERP(GPS)

GLONASS

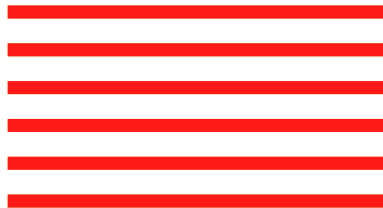


ERP(GLONASS)

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ERP(GPS)



ERP(GLONASS)



ERP(Combined)



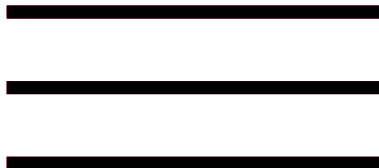
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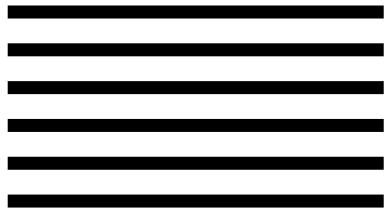
ERP(GLONASS)

ERP(Combined)

# Principle of Solution Generation

GPS

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GCC(GPS)

GCC(GLONASS)

GCC(Combined)

# Geocenter Parameters

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Introduction and Motivation

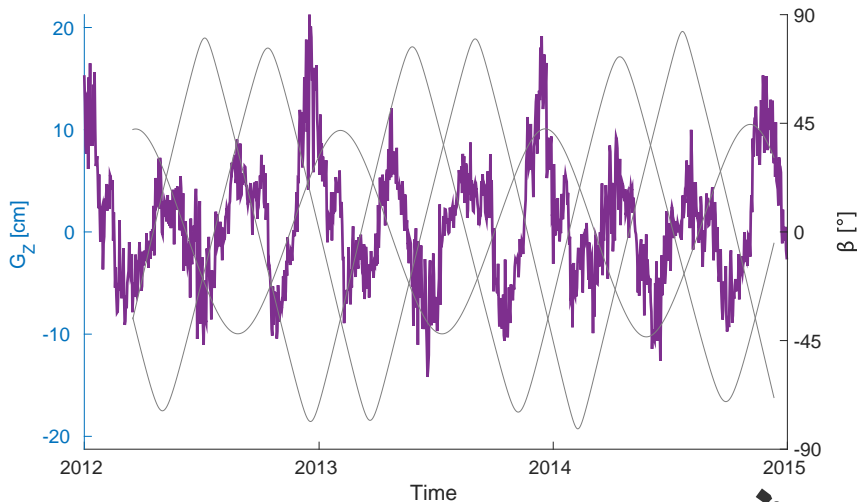
Geocenter Parameters

Earth Rotation Parameters

Summary and Conclusion

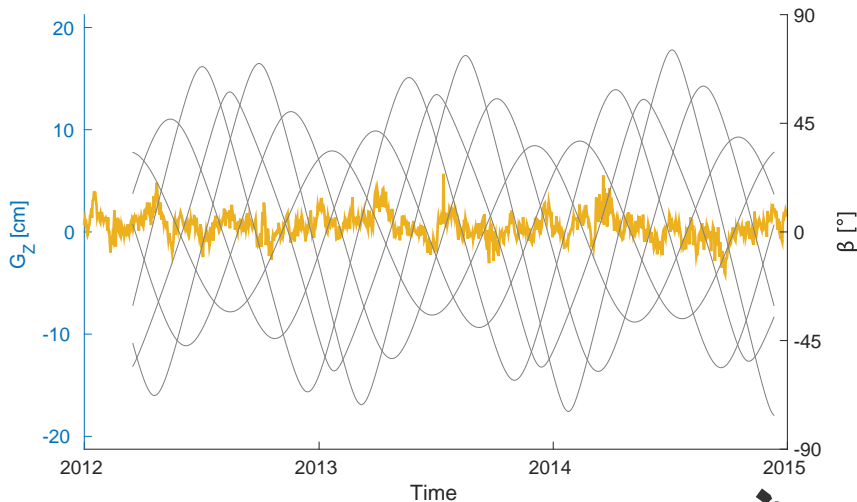
# Geocenter Parameters

Time series for GCC estimates: Z component from GLONASS



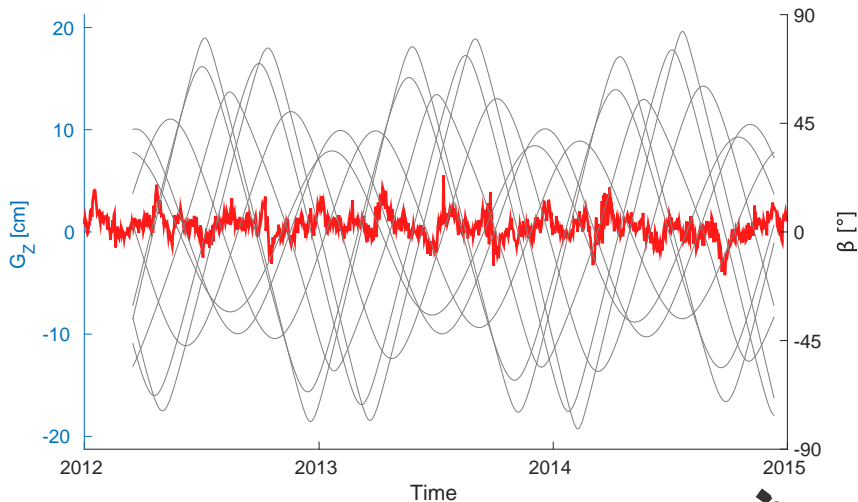
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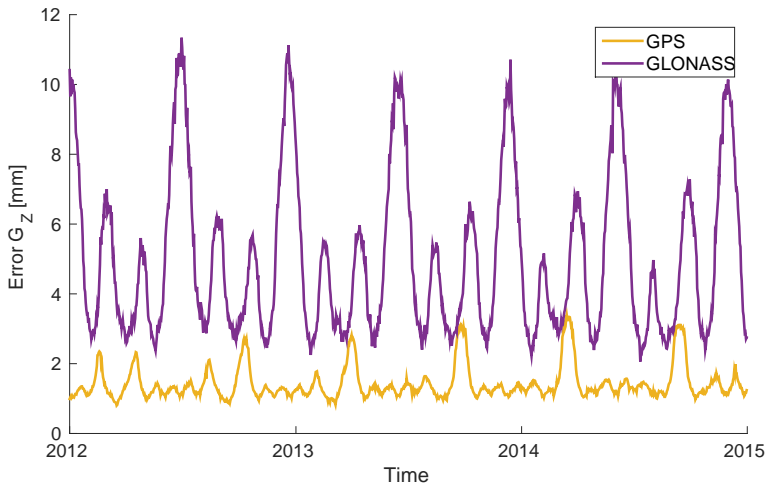
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Time series for GCC estimates: Z component from GPS+GLO



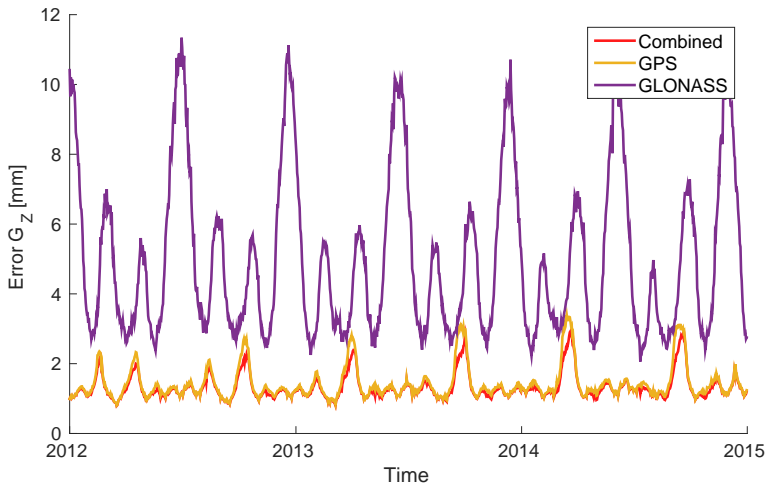
# Geocenter Parameters

## Formal errors for GCC estimates: Z component



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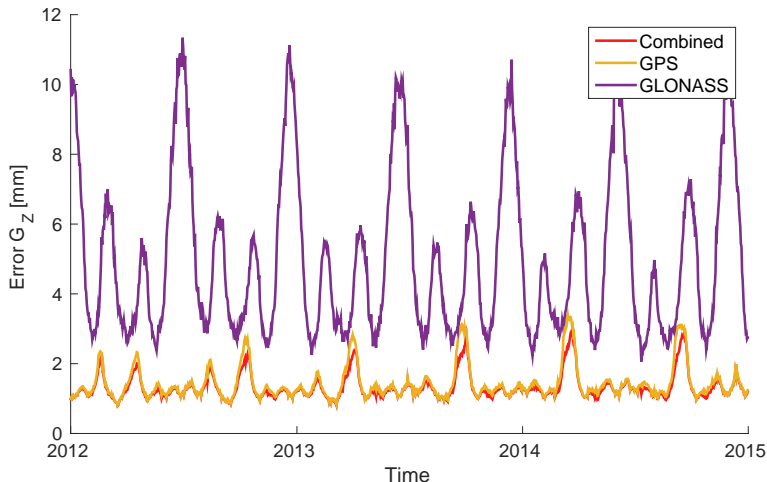
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In full agreement to Meindl et al., 2013: DOI 10.1016/j.asr.2012.10.026.

# Earth Rotation Parameters

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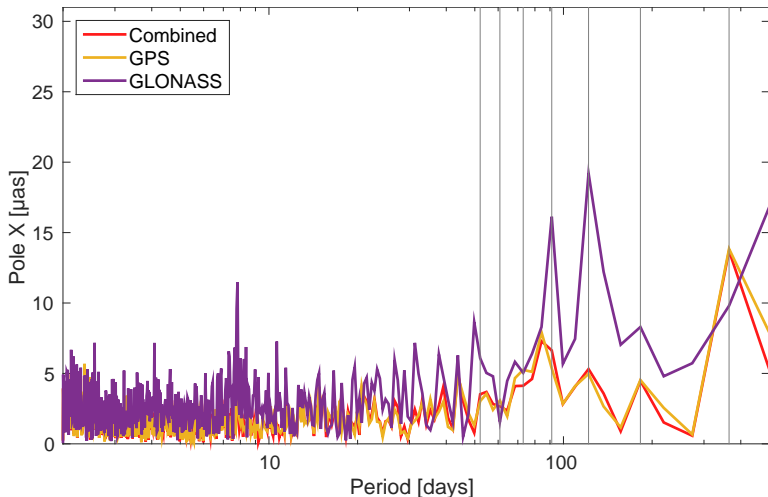
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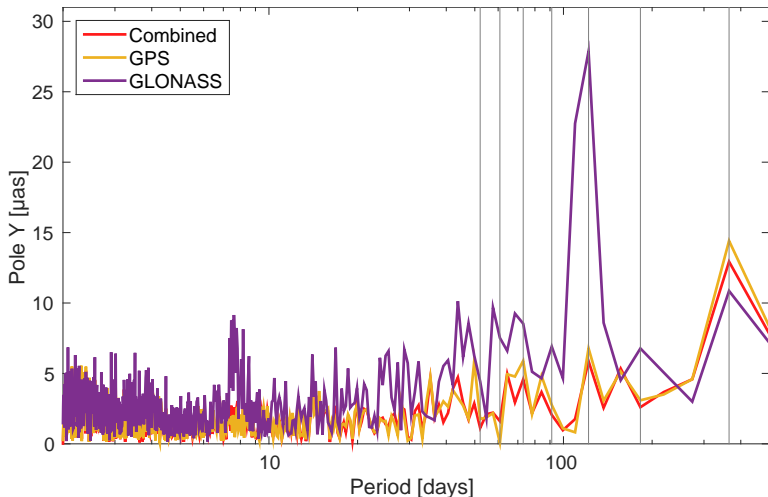
Amplitude spectra from ERP estimates: X component



Differences w.r.t. IERS C04 series (related to ITRF2008) have been analysed.

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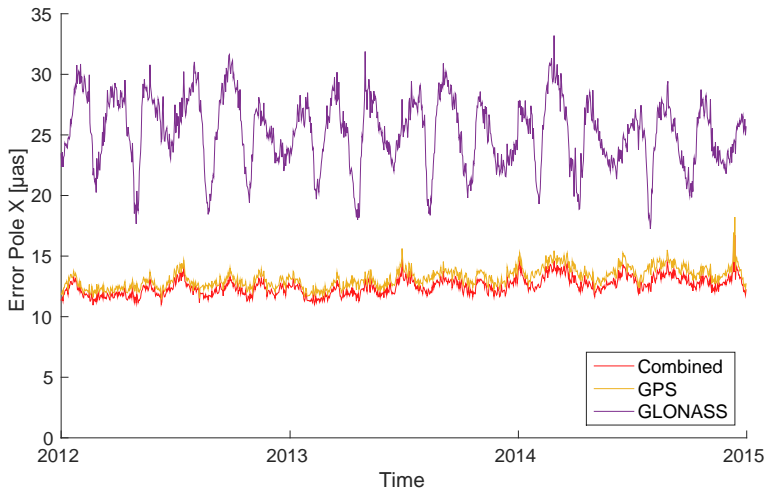
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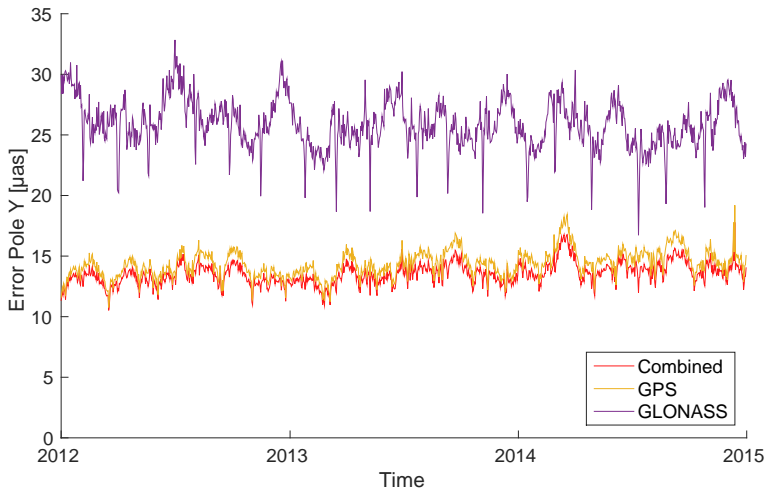
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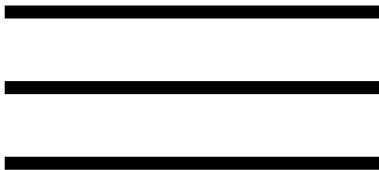
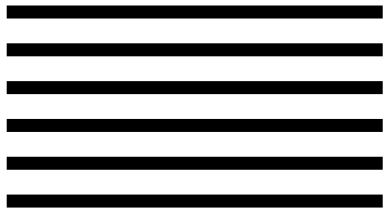
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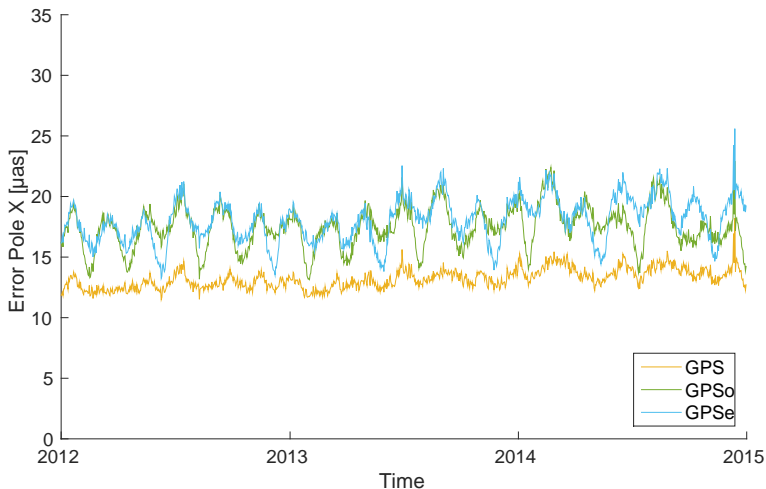
GLONASS





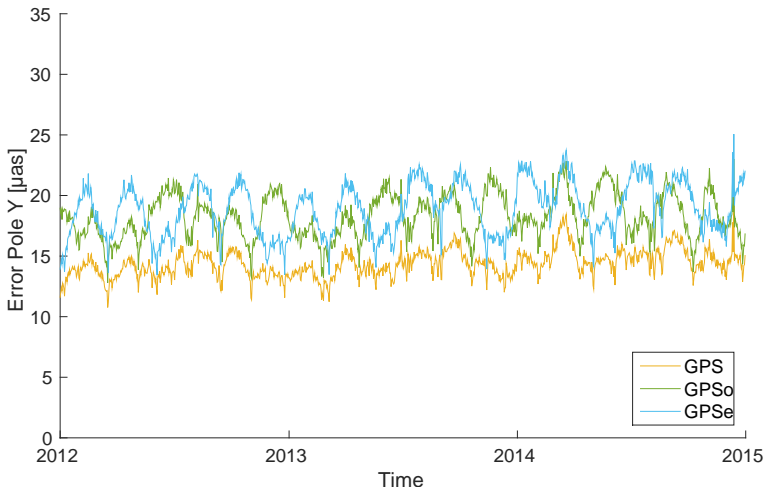
# GPS: Two Three-Plane Constellations

Formal errors for ERP estimates: X component



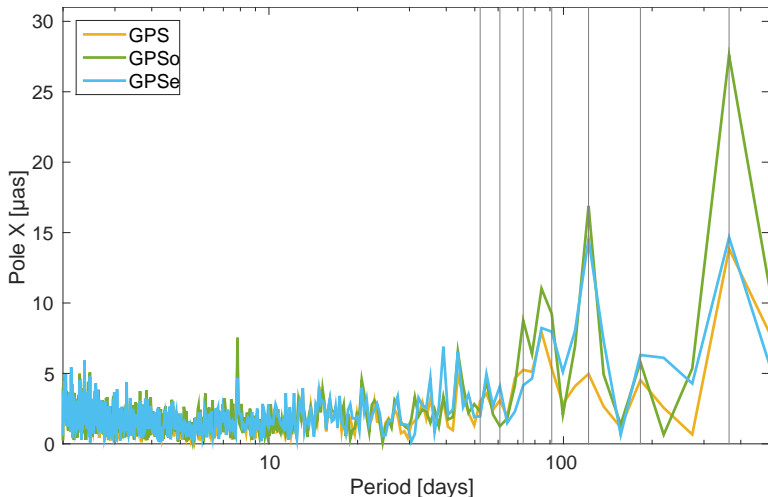
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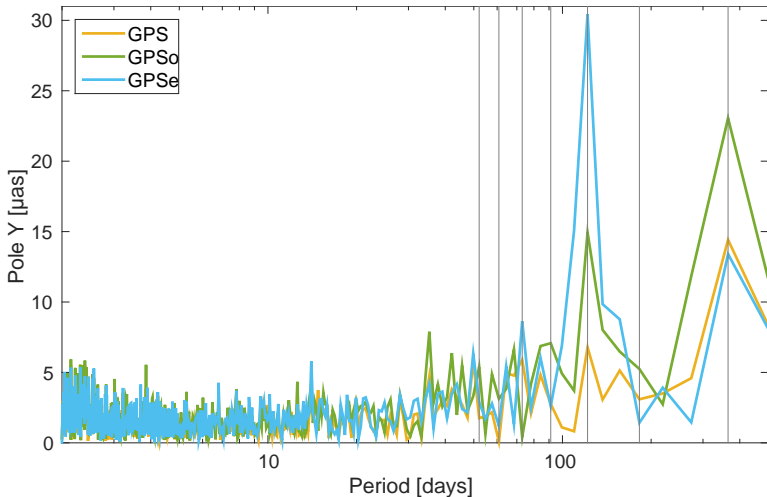
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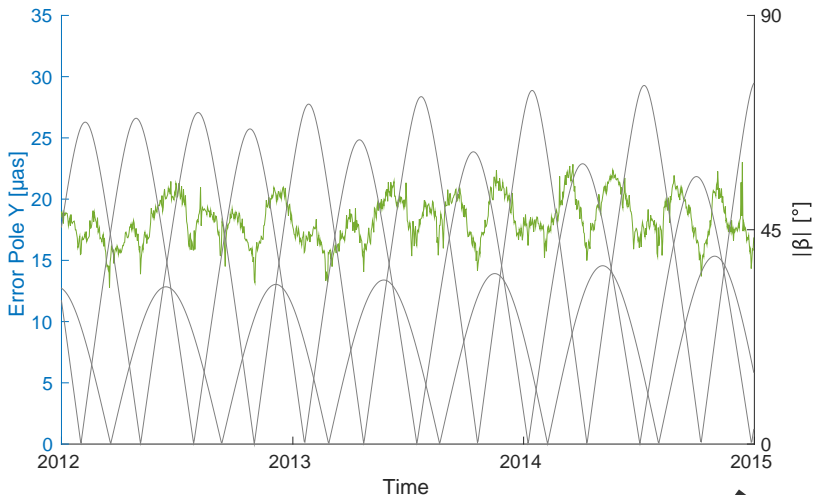
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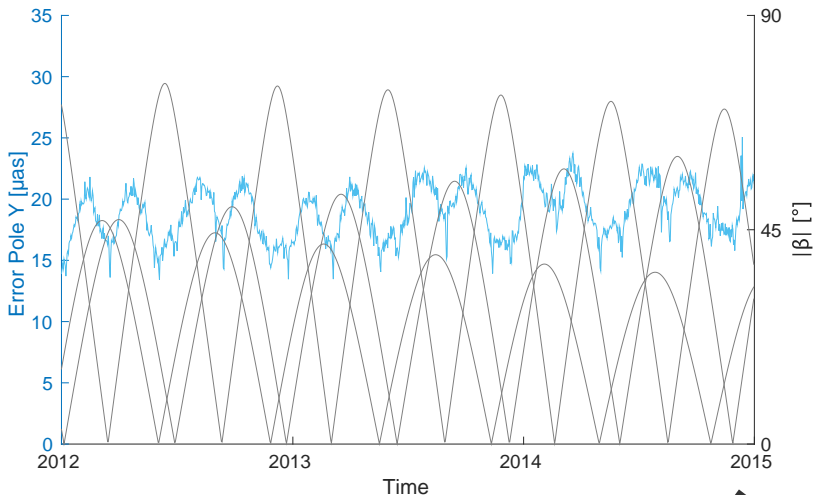
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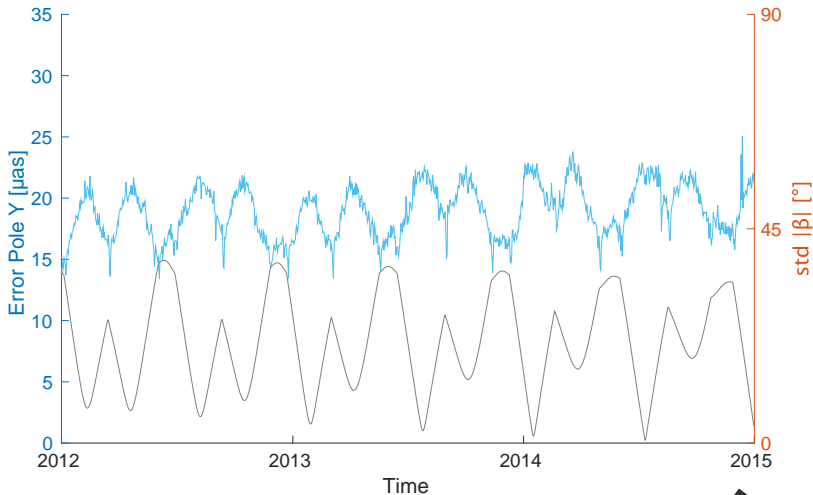
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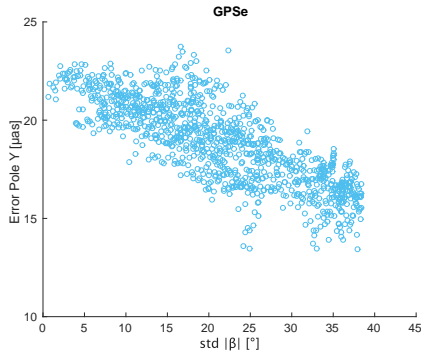
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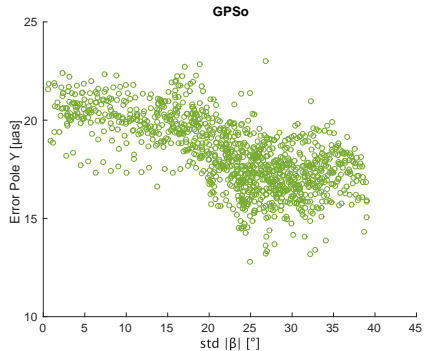
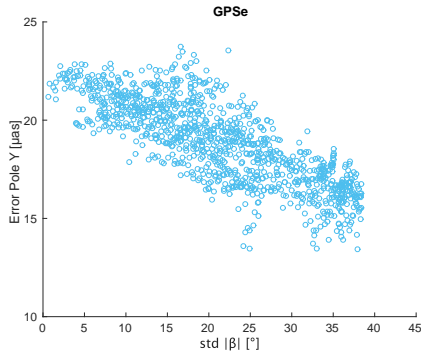
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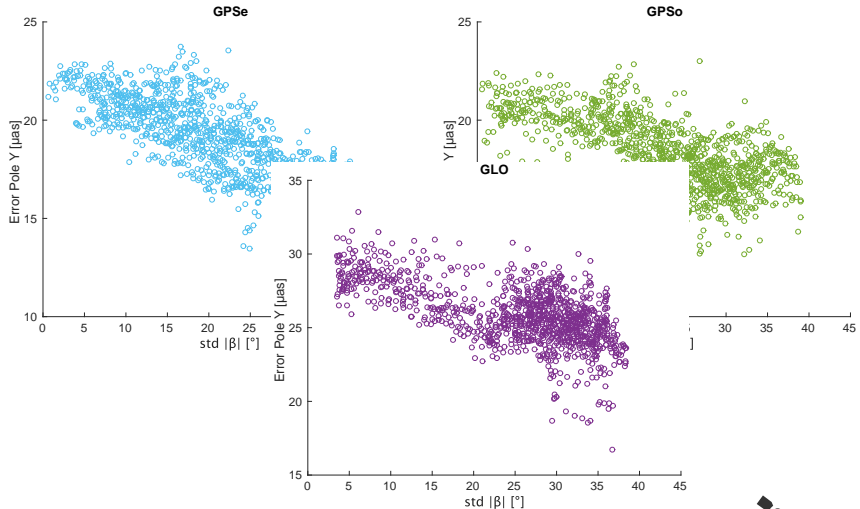
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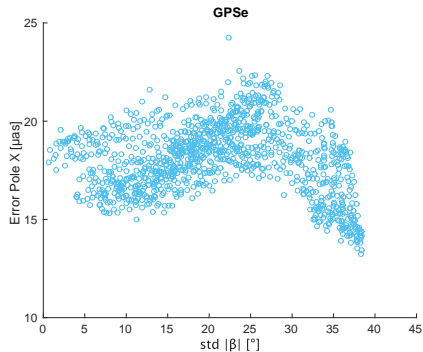
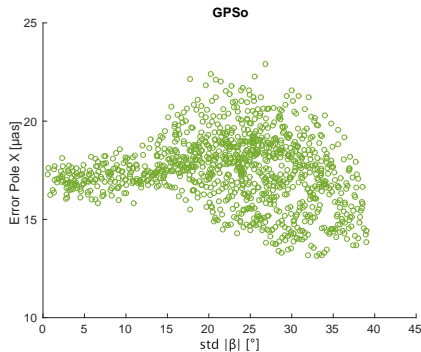
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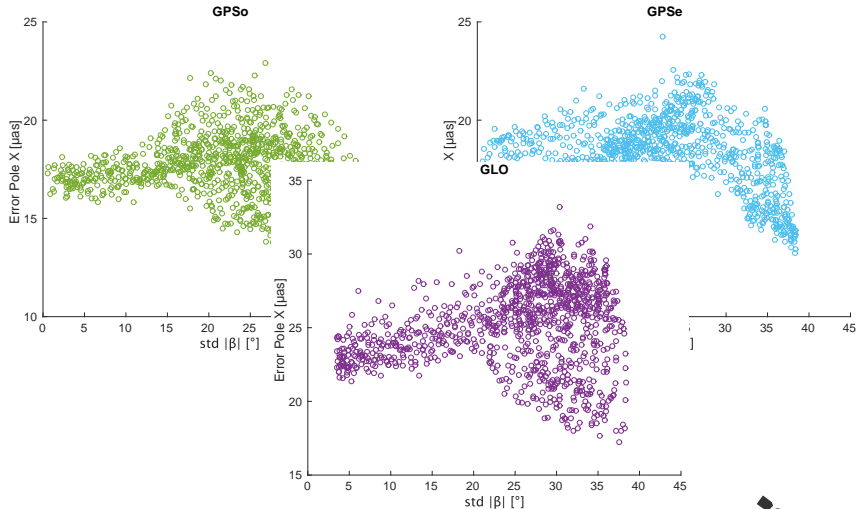
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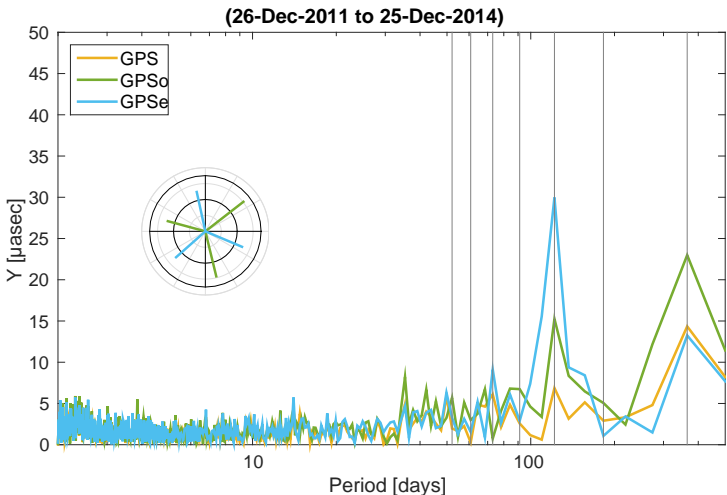
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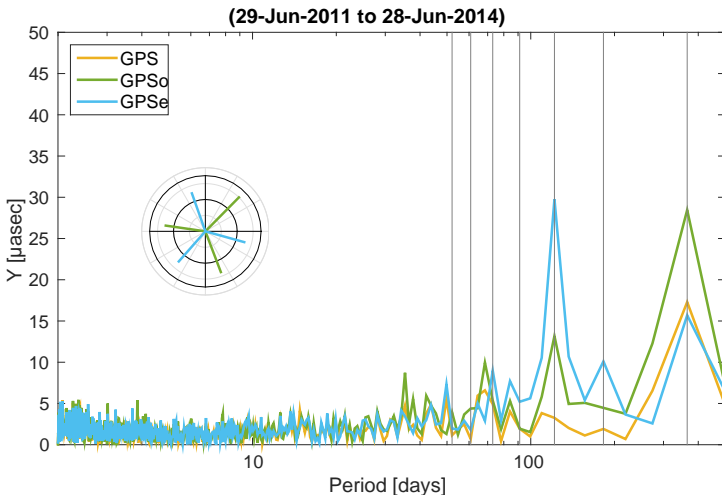
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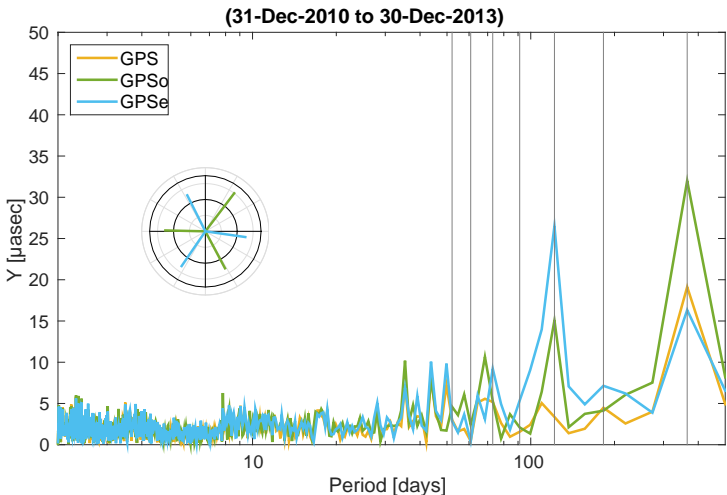
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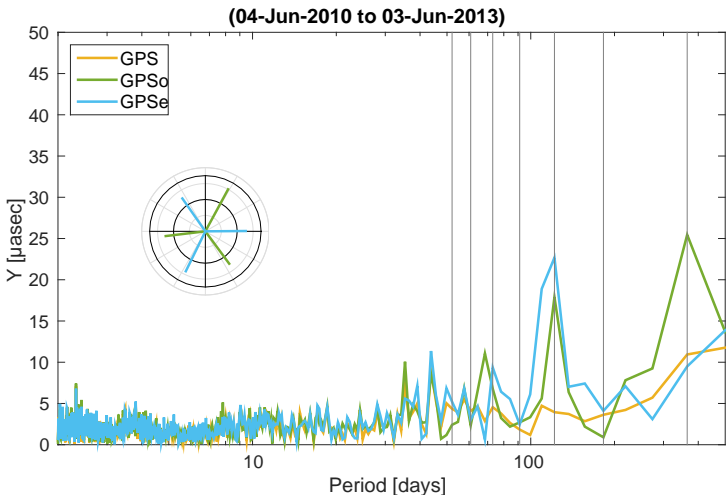
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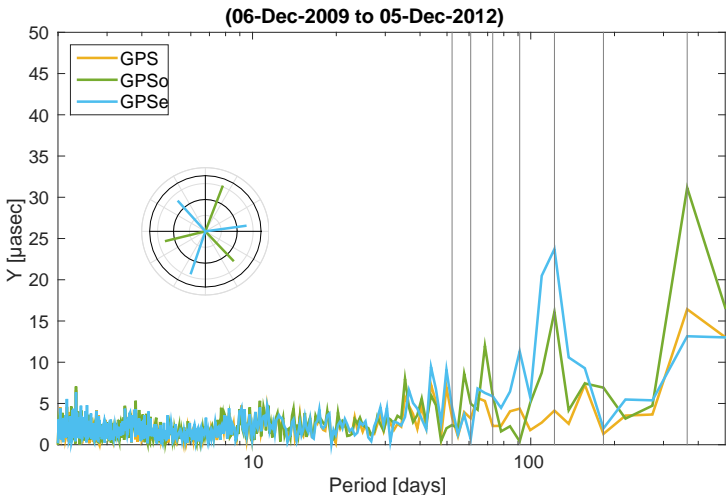
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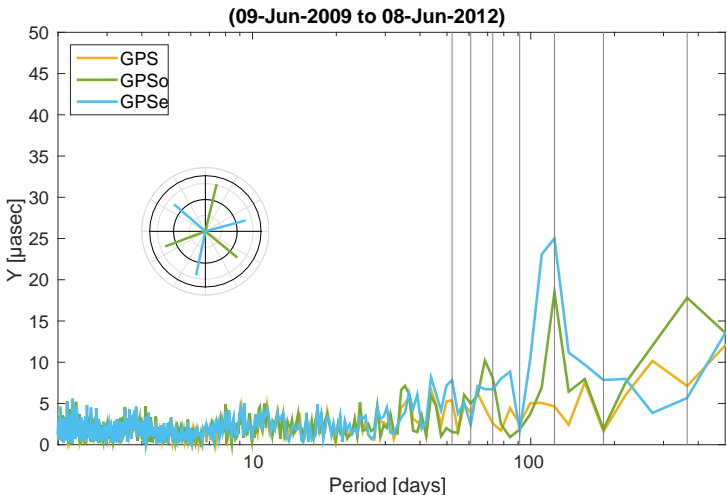
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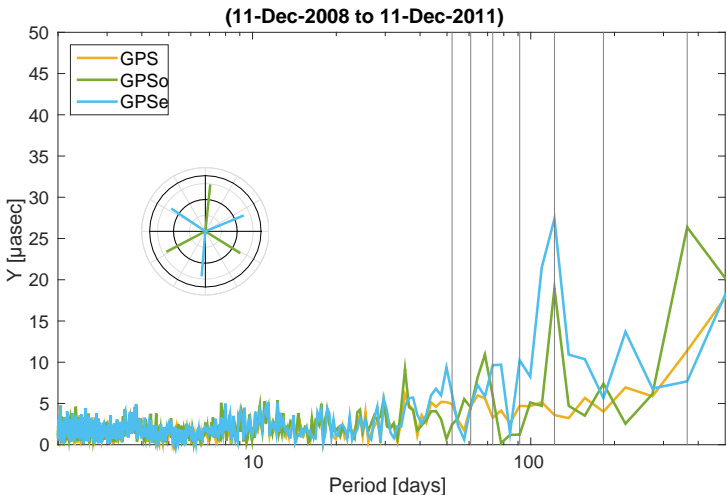
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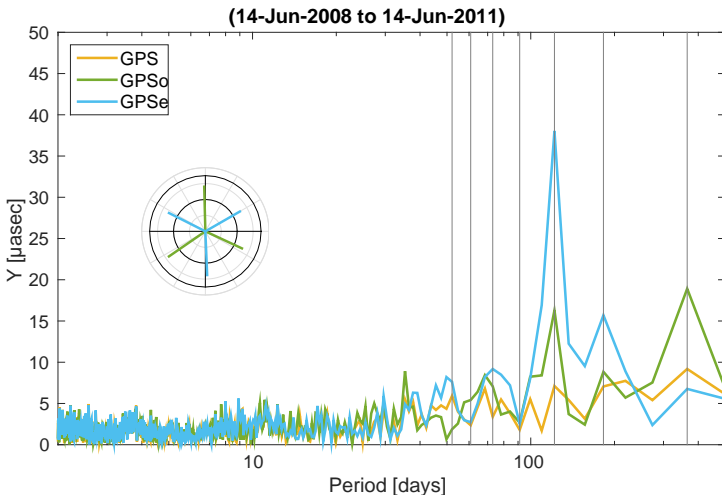
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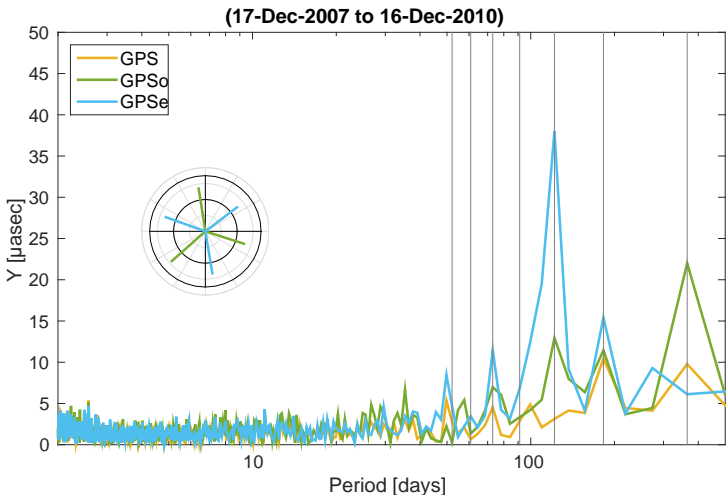
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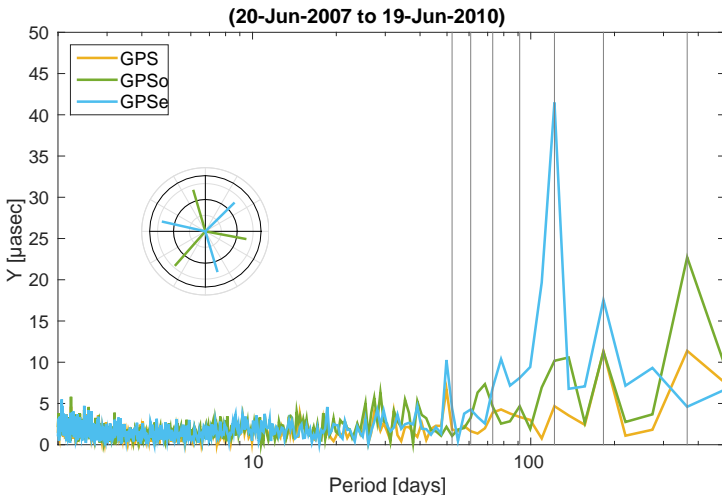
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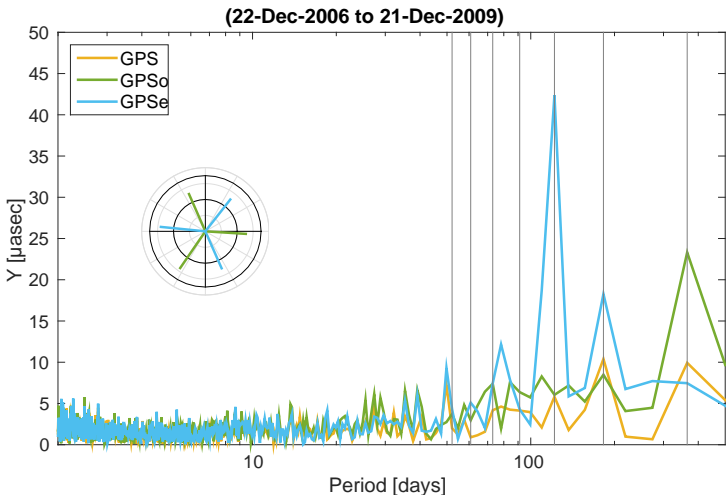
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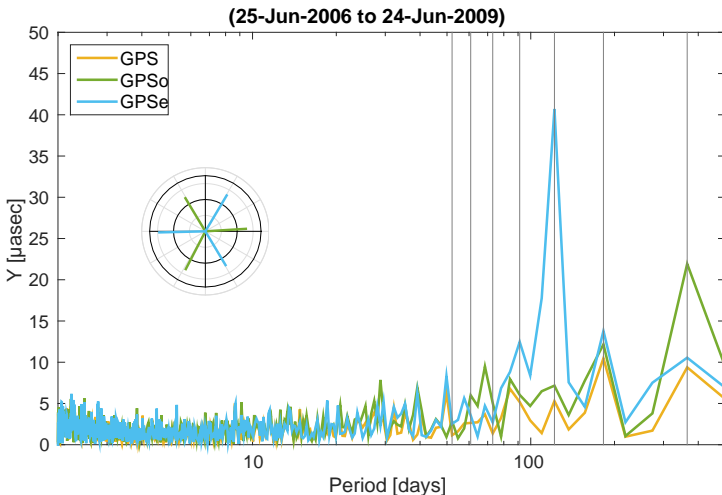
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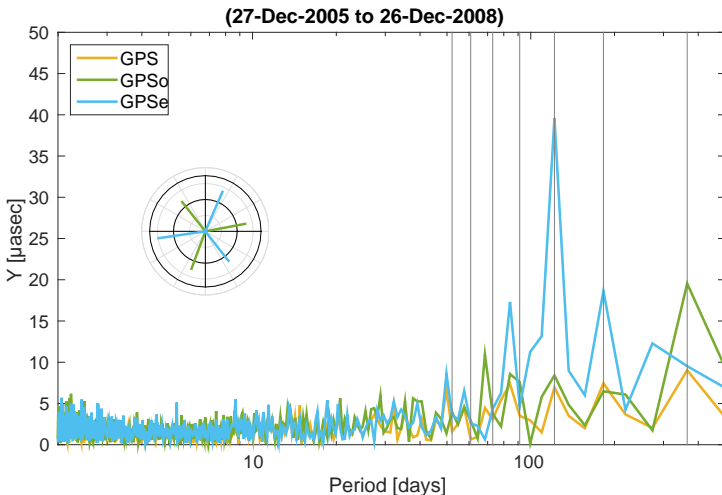


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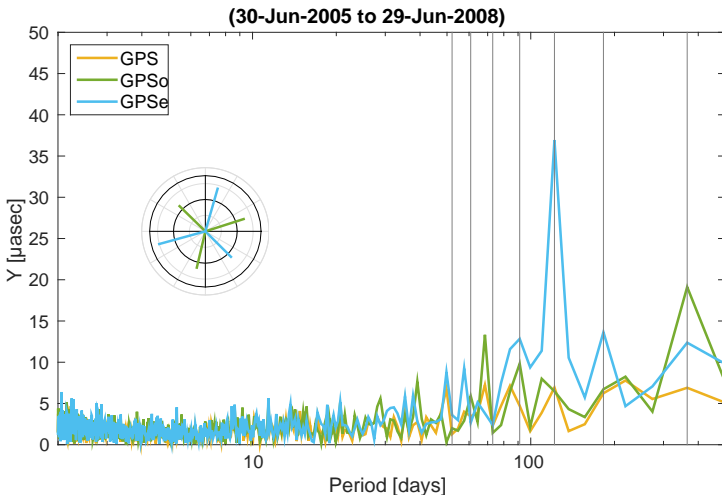
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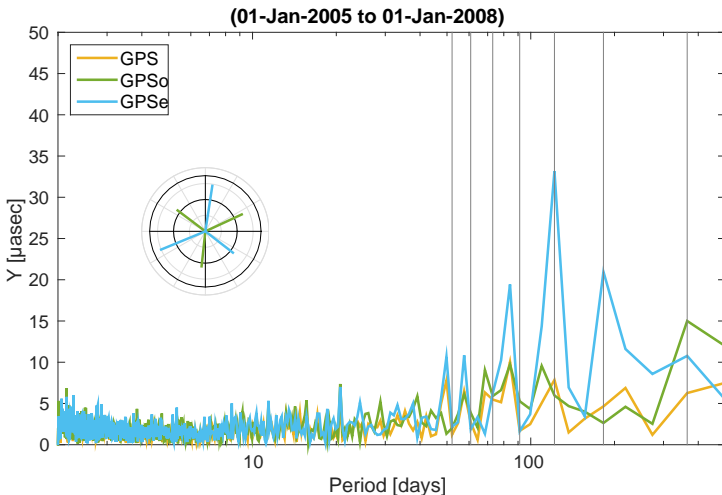
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# Summary and Conclusion

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- The setup of satellite-, plane-, or GNSS-specific ERP- and/or GCC-parameters was implemented.
  - It is enabled for internal purposes in the operational solution since May 2015 and the most recent reprocessing (see Poster by Sušnik et al.).
  - The results from a GNSS-specific setup on the NEQ-level are equivalent to independent GNSS-specific solutions.

# Summary and Conclusion

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- The setup of satellite-, plane-, or GNSS-specific ERP- and/or GCC-parameters was implemented.
- There is almost no contribution from GLONASS to a combined GPS+GLONASS GCC series (Z-component).
  - Meindl et al (2013): due to the inclination of GLONASS satellites ( $64^\circ$ ) the Sun may be almost perpendicular above the orbital plane, which results in a direct correlation with dynamic orbit parameters.

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- There is almost no contribution from GLONASS to a combined GPS+GLONASS GCC series (Z-component).
- The GLONASS contribution to the ERPs is mainly limited by the three-plane constellation.
  - The ERP results from the GLONASS constellation are comparable to solutions with a synthetic three-plane GPS constellation.
  - The geometric effect changes in time due to the regression of the nodes of the satellite's orbital planes.

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- There is almost no contribution from GLONASS to a combined GPS+GLONASS GCC series (Z-component).
- The GLONASS contribution to the ERPs is mainly limited by the three-plane constellation.
- Similar limitations may be expected for Galileo and the MEO-constellation of BeiDou.
- With a full multi-GNSS analysis the constellation effect should be heavily reduced, ideally eliminated.

# THANK YOU for your attention



Publications of the satellite geodesy research group:

<http://www.bernese.unibe.ch/publist>